Assignment 4 ROS

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**Running our code**

**This document assumes that ~/ros\_workspace/ is in your ROS\_PATH variable!**

**Contents of zip should be:**

**[folder] assignment4**

**+ .. <other files>**

Extract the zip into ~/ros\_workspace/

*Detect the package:*

rosdep update

(if needed, run rosdep init beforehand)

*Build the binary:*

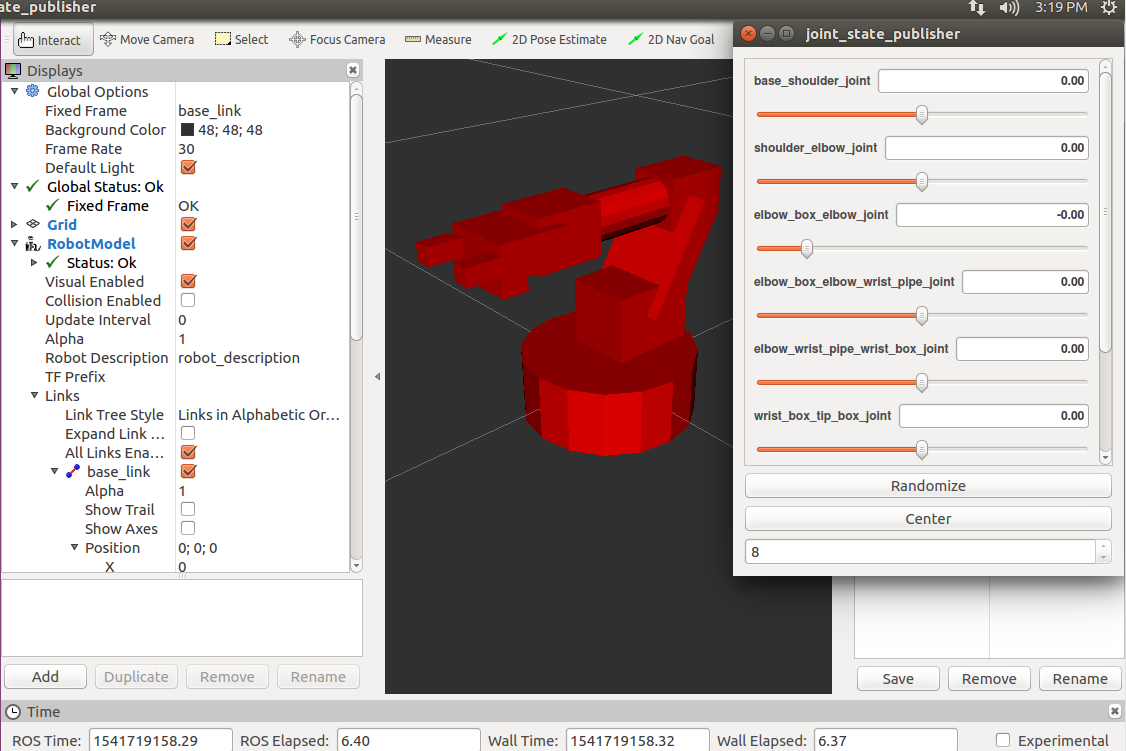
cd ~/ros\_workspace/assignment3

rosmake

*Then launch the package: (terminal1)*

roslaunch assignment4 assignment4.launch

Screen after running roslaunch command:



**Joints**

Joints can be manipulated so the robot arm can move, for example (centered and moved):

